

# ServoMaster: Metadata: controller/transition

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## 1. Definition

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`controller/transition` *feature* returns true if the hardware is capable of providing the hardware transition control.

Examples are Ohmark Digital Servo Controller, [AdvancedServo](#), and [Pololu](#) family.

There's a lot of possible transition types, which may or may not be defined later (in particular, *constant velocity* and *constant acceleration*). At this time, this feature is rather for informational purposes.